

On almost resonant elliptic problems ¹

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The main problem

We consider the following system:

$$\begin{cases} -\Delta u = au + bv \pm (f_1(x, v) + h_1(x)) & \text{in } \Omega, \\ -\Delta v = bu + av \pm (f_2(x, u) + h_2(x)) & \text{in } \Omega, \\ u(x) = v(x) = 0 & \text{on } \partial\Omega, \end{cases} \quad (1.1\pm)$$

where

- $\Omega \subset \mathbb{R}^N$ bounded domain,
- $a, b \in \mathbb{R}$,
- $h_1, h_2 \in L^2(\Omega)$,
- $f_1, f_2 : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ sublinear Carathéodory functions:
 $\exists S > 0, q \in (1, 2)$, such that $|f_i(x, t)| \leq S(1 + |t|^{q-1})$, $i = 1, 2$.

Purpose: to obtain multiplicity of solutions, when the linear part is “near resonance”: that is, $a + b$ or $a - b$ near some eigenvalue λ_k .



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Motivation: the scalar problem

Main motivation: de Paiva, M. [dPM08]: for the scalar equivalent

$$\begin{cases} -\Delta u = \lambda u \pm f(x, u) + h(x) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega, \end{cases} \quad (1.2\pm)$$

where $h \in L^2(\Omega)$, f is sublinear, and

$$\begin{cases} \lim_{|t| \rightarrow \infty} F(x, t) = +\infty \text{ uniformly } x \in \Omega, \\ \int_{\Omega} h \phi \, dx = 0 \quad \forall \phi \in H_{\lambda_k}. \end{cases}$$

it was proved that

- there exists $\varepsilon_0 > 0$, such that, if $\lambda \in (\lambda_k - \varepsilon_0, \lambda_k)$, then two solutions exist for problem (1.2+);
- there exists $\varepsilon_1 > 0$, such that, if $\lambda \in (\lambda_k, \lambda_k + \varepsilon_1)$ then two solutions exist for problem (1.2-).



The results for the system

For our system we assume an analogous condition:

$$\begin{cases} (i) & \lim_{|t| \rightarrow \infty} F_i(x, t) = +\infty, \text{ unif. with resp. to } x \in \Omega, i = 1, 2, \\ (ii) & \int_{\Omega} h_1 \phi + h_2 \psi = 0, \text{ for every } (\phi, \psi) \in Z, \end{cases} \quad (\mathbf{F})$$

Theorem

Assume the given hypotheses, let $\lambda_k, \lambda_l \in \sigma(-\Delta)$,

$$Z = \text{span} \{ (\phi, \phi) : \phi \in H_{\lambda_k} \}.$$

Then

- (a) Given $\delta > 0$, there exists $\varepsilon_0 > 0$ such that, if $a - b \in (\lambda_{l-1} + \delta, \lambda_l - \delta)$ and $a + b \in (\lambda_k - \varepsilon_0, \lambda_k)$, then Problem (1.1+) has two distinct solutions.
- (b) Given $\delta > 0$, there exists $\varepsilon_1 > 0$ such that, if $a - b \in (\lambda_{l-1} + \delta, \lambda_l - \delta)$ and $a + b \in (\lambda_k, \lambda_k + \varepsilon_1)$, then Problem (1.1-) has two distinct solutions.



Theorem

Assume the given hypotheses, let $\lambda_k, \lambda_l \in \sigma(-\Delta)$,

$$Z = \text{span} \{ (\phi, -\phi) : \phi \in H_{\lambda_k} \}.$$

Then

- (a) Given $\delta > 0$, there exists $\varepsilon_0 > 0$ such that, if $a + b \in (\lambda_{l-1} + \delta, \lambda_l - \delta)$ and $a - b \in (\lambda_k - \varepsilon_0, \lambda_k)$, then Problem (1.1-) has two distinct solutions.
- (b) Given $\delta > 0$, there exists $\varepsilon_1 > 0$ such that, if $a + b \in (\lambda_{l-1} + \delta, \lambda_l - \delta)$ and $a - b \in (\lambda_k, \lambda_k + \varepsilon_1)$, then Problem (1.1+) has two distinct solutions.



Double resonance

Theorem

Assume the given hypotheses, let $\lambda_k, \lambda_l \in \sigma(-\Delta)$ (may be the same) and $Z = \text{span}\{(\phi, \phi) : \phi \in H_{\lambda_k}, (\phi, -\phi) : \phi \in H_{\lambda_l}\}$. Then

- (e) there exists $\varepsilon_2 > 0$ such that, if $a - b \in (\lambda_l, \lambda_l + \varepsilon_2)$ and $a + b \in (\lambda_k - \varepsilon_2, \lambda_k)$, then problem (1.1+) has two distinct solutions.

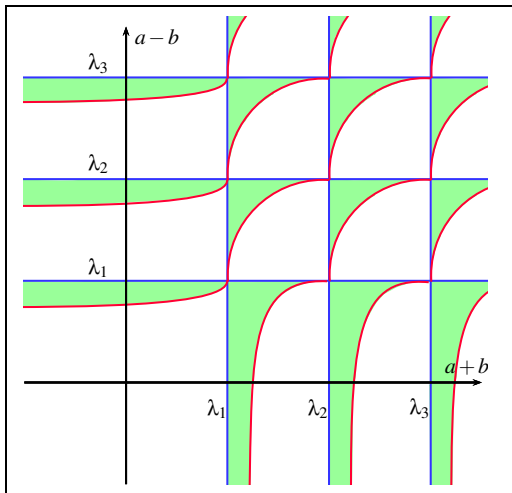
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- (f) there exists $\varepsilon_2 > 0$ such that, if $a - b \in (\lambda_k - \varepsilon_2, \lambda_k)$ and $a + b \in (\lambda_l, \lambda_l + \varepsilon_2)$, then problem (1.1-) has two distinct solutions.



Figure: Sketch of the regions with two solutions for problem (1.1–)





More literature

- **Scalar problem:**
 - λ_1 , *ODE*, bifurcation and degree. Mawhin-Schmitt (1990), Badiale-Lupo (1989), Lupo-Ramos (1990)
 - λ_1 , *PDE*, bifurcation and degree. Chiappinelli-Mawhin-Nugari (1992), Chiappinelli-de Figueiredo (1993),
 - λ_1 , *PDE*, variational techniques. Ramos-Sanchez (1997), Ma-Ramos-Sanchez (1997), Ma-Pelicer (2002) (p -Laplacian)
 - λ_k , *ODE*, bifurcation and degree. Lupo-Ramos (1990)
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- **Systems**
 - in gradient form. Ou-Tang (2009), Suo-Tang (2010), An-Suo (2012),
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Background

For the problem

$$\begin{cases} -\Delta u = \lambda u + h(x) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega, \end{cases} \quad (1.1)$$

one has

- If λ is NOT an eigenvalue: there there exists a **unique solution**.
- If $\lambda = \lambda_k$ is an eigenvalue: there exists **no solution or infinite solutions** (depending if $\int_{\Omega} h \phi dx \neq 0$ or $= 0 \quad \forall \phi \in H_{\lambda_k}$)

However, the solution when $\lambda \in (\lambda_k, \lambda_k + \varepsilon_1)$ and the solution when $\lambda \in (\lambda_k - \varepsilon_1, \lambda_k)$ are "different" in several ways.



Variational methods

In order to find a solutions of

$$\begin{cases} -\Delta u = f(x, u) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega. \end{cases} \quad (1.2)$$

We define a functional $J : H_0^1(\Omega) \rightarrow \mathbb{R}$:

$$J(u) = \frac{1}{2} \int_{\Omega} |\nabla u|^2 - \int_{\Omega} F(x, u)$$

(under suitable hypotheses) it turns out that J is smooth and **critical points of J** (i.e. $u : J'(u) = 0$) and **solutions of the equation**, are the same thing.

So: **how do we find critical points of J ?**

Example: $J : \mathbb{R} \rightarrow \mathbb{R}$, $J \in \mathcal{C}^1(\mathbb{R})$, $\lim_{t \rightarrow \pm\infty} J(t) = +\infty$
implies J has a global minimum, which is a critical point.



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Variational methods

Some classical Critical point theorems:

Definition

$J \in C^1(E, \mathbb{R})$ satisfies the **PS condition**:

For each sequence $\{u_n\} \subseteq E$ such that $|J(u_n)| \leq C$ and $J'(u_n) \rightarrow 0$ there exists a (strongly) convergent subsequence.

Theorem (Mountain Pass Theorem)

- 1 E Banach space; $I \in C^1(E, \mathbb{R})$ satisfies the PS condition;
- 2 $I(0) = 0$;
- 3 $\exists \rho, \alpha > 0$ such that $I(u) \geq \alpha$ for all u such that $\|u\|_E = \rho$;
- 4 $\exists e \in E$ such that $\|e\|_E > \rho$ and $I(e) < 0$.

Moreover, let

- $\Gamma = \{\gamma \in C^0([0, 1]; E) \text{ such that } \gamma(0) = 0 \text{ and } \gamma(1) = e\}$;
- $c = \inf_{\gamma \in \Gamma} \sup_{t \in [0, 1]} I(\gamma(t))$.

Then $c \geq \alpha$ and there exists a critical point at level c .



Variational methods

Theorem (Saddle Point Theorem)

- 1 E Banach space; $I \in C^1(E, \mathbb{R})$ satisfies the PS condition;
- 2 $E = V \oplus W$ with $\dim(V) < \infty$;
- 3 $\exists \beta < \alpha$ and $\rho > 0$ such that
 - $I(u) \geq \alpha$ for all $u \in W$;
 - $I(u) \leq \beta$ for all $u \in B_\rho^V = \{u \in V, \|u\| = \rho\}$;

Moreover, let

- $\Gamma = \{\gamma \in C^0(B_\rho^V; E) \text{ such that } \gamma|_{\partial B_\rho^V} = id\}$
- $c = \inf_{\gamma \in \Gamma} \sup_{t \in [0,1]} I(\gamma(t))$.

Then $c \geq \alpha$ and there exists a critical point at level c .



Variational methods

Let $\lambda \in (\lambda_{k-1}, \lambda_k)$ and consider again

$$\begin{cases} -\Delta u = \lambda u + h(x) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega, \end{cases} \quad (1.3)$$

Let

$$V = \bigoplus_{i=1}^{k-1} H_{\lambda_i} \quad W = V^\perp$$

$$J(u) = \frac{1}{2} \int_{\Omega} |\nabla u|^2 - \frac{\lambda}{2} \int_{\Omega} u^2 - \int_{\Omega} hu$$

By properties of the eigenspaces

$$\int_{\Omega} |\nabla u|^2 \leq \lambda_{k-1} \int_{\Omega} u^2 \quad \text{in } V \quad \int_{\Omega} |\nabla u|^2 \geq \lambda_k \int_{\Omega} u^2 \quad \text{in } W$$

In the end one gets the conditions of the Saddle Point Theorem.

If $\lambda \in (\lambda_{k-1}, \lambda_k)$ it is the same... but with different spaces involved!



Scalar problem

Let us go back to the scalar problem in [dPM08]:

$$\begin{cases} -\Delta u = \lambda u \pm f(x, u) + h(x) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega, \end{cases} \quad (1.2\pm)$$

where $h \in L^2(\Omega)$, f is sublinear, and

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How do we prove that there exists $\varepsilon_0 > 0$, such that, if $\lambda \in (\lambda_k - \varepsilon_0, \lambda_k)$, then two solutions exist for problem (1.2+)?

The idea below this kind of problem is the following: passing the eigenvalue the saddle point geometry changes: near the eigenvalue the perturbation f makes it possible to have both saddle geometries at the same time.



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Some notation

Functional:

$$J^\pm : H_0^1(\Omega) \rightarrow \mathbb{R} :$$

$$J(u) = \frac{1}{2} \int_{\Omega} (|\nabla u|^2 - \lambda u^2) dx \mp \int_{\Omega} F(x, u) dx - \int_{\Omega} h u dx$$

$$V = \text{span}\{\phi_1, \dots, \phi_{k-1}\},$$

$$Z = \text{span}\{\phi_k, \dots, \phi_{k+m-1}\} = H_{\lambda_k},$$

$$W = (V \oplus Z)^\perp,$$

S_V, S_{VZ}, S_{ZW} , the unit spheres in $V, V \oplus Z, Z \oplus W$

B_V, B_{VZ}, B_{ZW} , the unit balls.

If $\lambda \notin \sigma(-\Delta)$ there exists a solution from Saddle Point Theorem.

however, a suitable behaviour of f may give rise to a further solution.



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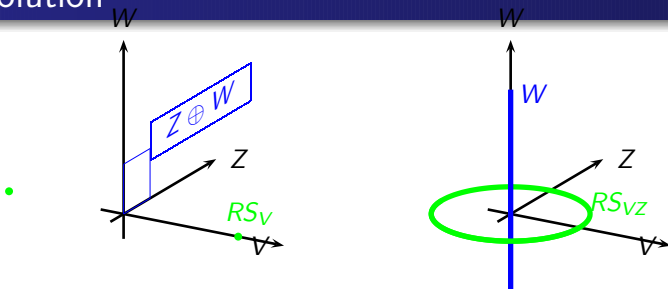
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scalar

One solution



$$(\lambda < \lambda_k) \quad c_{k-1} = \inf_{\gamma \in \Gamma_{k-1}} \sup_{v \in RB_V} J(\gamma(v)).$$

$$\Gamma_{k-1} = \{\gamma \in C^0(RB_V; H_0^1) \text{ s.t. } \gamma|_{RS_V} = Id\},$$

$$(\lambda > \lambda_k) \quad c_k = \inf_{\gamma \in \Gamma_k} \sup_{v \in RB_{VZ}} J(\gamma(v)).$$

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The case $\lambda < \lambda_k$

Proposition

In the given hypotheses:

$$\exists D_W : J^+(u) \geq D_W \quad \text{for } u \in W; \quad (1.4)$$

there exist $R^+, \varepsilon_0 > 0$ such that, for any $\lambda \in (\lambda_k - \varepsilon_0, \lambda_k)$

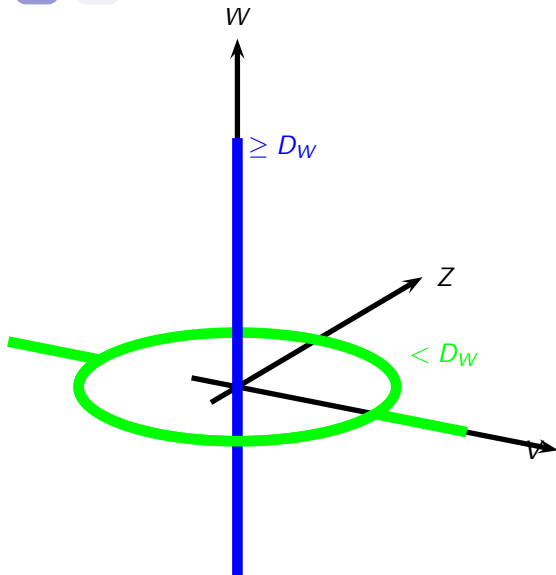
$$J^+(u) < D_W \quad \text{for } u \in R^+ S_{VZ}, \quad (1.5)$$

$$\text{for } u \in V, \|u\| \geq R^+; \quad (1.6)$$

if now we fix $\lambda \in (\lambda_k - \varepsilon_0, \lambda_k)$ then

$$\exists D_\lambda : J^+(u) \geq D_\lambda \quad \text{for } u \in Z \oplus W, \quad (1.7)$$

$$\exists \rho_\lambda^+ > R^+ : J^+(u) < D_\lambda \quad \text{for } u \in \rho_\lambda^+ S_V. \quad (1.8)$$



We have

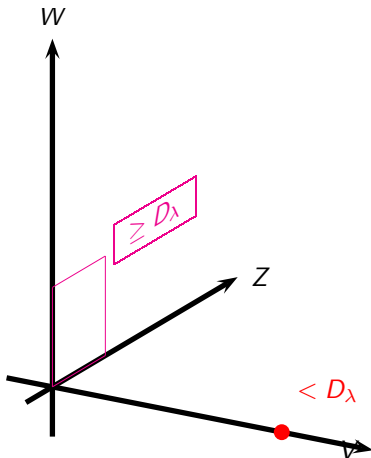
$$c_k \geq D_W,$$

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but also

$$c_{k-1} < D_W,$$

then the solutions are distinct.



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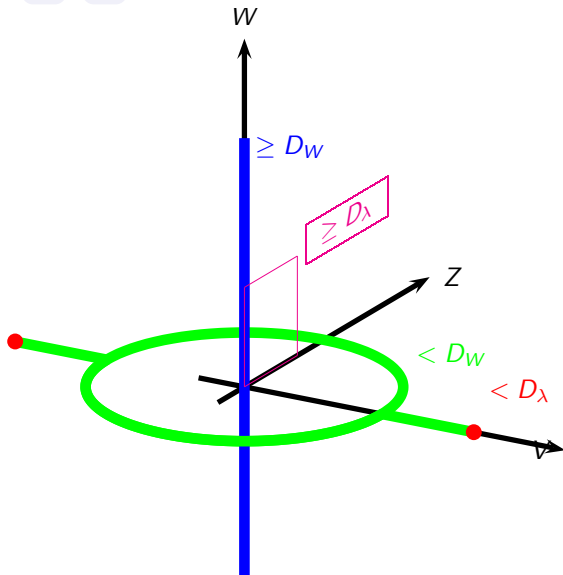
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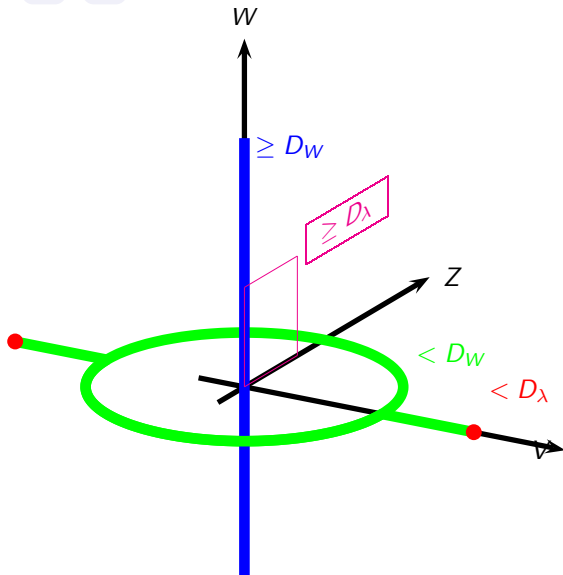
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Remarks:

- The system is of Hamiltonian type; then variational but with **strongly indefinite functional**: we use a Galerkin approximation.
- In the scalar case we had a different proof for the case above or below the eigenvalue (saddle point theorems or linking spheres theorem, depending if the almost resonant eigenspace is part of the finite / infinite dimensional subspace in the splitting). For the system, having to use Galerkin approximation, **the geometry is always the same**: a finite dimensional saddle point.



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Idea of the Proof

We consider the functionals

$$J_{a,b}^{\pm}(u, v) = \pm \frac{1}{2} B_{a,b}((u, v), (u, v)) - \mathcal{F}(u, v) - \mathcal{H}(u, v). \quad (2.1)$$

defined in $E = H_0^1(\Omega) \times H_0^1(\Omega)$, where

$$\mathcal{F}(u, v) = \int_{\Omega} F_1(x, v) + \int_{\Omega} F_2(x, u), \quad \mathcal{H}(u, v) = \int_{\Omega} h_1 v + \int_{\Omega} h_2 u,$$

$$B_{a,b}((u, v), (\phi, \psi)) = \int_{\Omega} \nabla u \nabla \psi + \int_{\Omega} \nabla v \nabla \phi - a \int_{\Omega} (u\psi + v\phi) - b \int_{\Omega} (u\phi + v\psi).$$

We consider the eigenvalues and eigenfunctions of B :

$$\mu_{\pm i} = \frac{-b \pm (\lambda_i - a)}{\lambda_i}, \quad \psi_{\pm i} = \frac{(\phi_i, \pm \phi_i)}{\sqrt{2\lambda_i}}, \quad i \in \mathbb{N}.$$

Then

$$\|\psi_i\|_E = 1, \quad \langle \psi_i, \psi_j \rangle_E = \delta_{i,j}, \quad B(\psi_i, \psi_j) = \mu_i \delta_{i,j}, \quad i, j \in \mathbb{Z}_0 = \mathbb{Z} \setminus \{0\}.$$

$$a \pm b = \lambda_i \Rightarrow \mu_{\pm i} = 0 \quad (2.2)$$

So we define

$V = \overline{\text{span}\{\psi_i : i \in \mathbb{Z}_0, \mu_i < 0\}}$: negative subspace

$Z = \overline{\text{span}\{\psi_i : i \in \mathbb{Z}_0, \mu_i = \mu_k\}}$: almost resonant subspace

$W = \overline{\text{span}\{\psi_i : i \in \mathbb{Z}_0, \mu_i > 0 \text{ e } \mu_i \neq \mu_k\}}$

B_V, B_{VZ}, B_W, B_{ZW} closed unitary balls in $V, V \oplus Z, W$ e $Z \oplus W$

S_V, S_{VZ}, S_W e S_{ZW} their relative boundaries



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$Z = \overline{\text{span}\{\psi_i : i \in \mathbb{Z}_0, \mu_i = \mu_k\}}$: almost resonant subspace

$W = \overline{\text{span}\{\psi_i : i \in \mathbb{Z}_0, \mu_i > 0 \text{ e } \mu_i \neq \mu_k\}}$

B_V, B_{VZ}, B_W, B_{ZW} closed unitary balls in $V, V \oplus Z, W$ e $Z \oplus W$

S_V, S_{VZ}, S_W e S_{ZW} their relative boundaries



$$E_n = \text{span}[\psi_{-n}, \dots, \psi_n] \subseteq E,$$

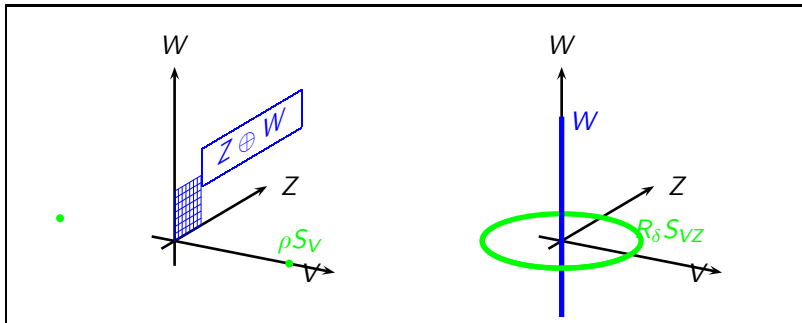
$$V_n = V \cap E_n \text{ e } W_n = W \cap E_n \\ (Z \subseteq E_n, \text{ for every } n > k + m)$$

J_n^+ the functional J^+ restricted to the subspace E_n .



Two Saddle Geometries

Let λ_k be the first eigenvalue above $a + b$ and $\text{dist}(a - b, \sigma) > \delta$.



$$a + b \notin \sigma(-\Delta)$$

$$J^+(\mathbf{u}) \geq D_{a+b, \delta}, \quad \mathbf{u} \in Z \oplus W$$

$$J^+(\mathbf{u}) < D_{a+b, \delta}, \quad \mathbf{u} \in \rho S_V, \quad \rho \geq \rho_{a+b, \delta}$$

$$a + b \nearrow \lambda_k \Leftrightarrow \mu_k \searrow 0$$

$$J^+(\mathbf{u}) \geq E_\delta, \quad \mathbf{u} \in W,$$

$$J^+(\mathbf{u}) < E_\delta, \quad \mathbf{u} \in R_\delta S_V Z$$



Proposition

Let λ_k be the first eigenvalue above $a + b$ and $\text{dist}(a - b, \sigma(-\Delta)) > \delta$.
Then

- There exists $E_\delta \in \mathbb{R}$, such that

$$J^+(\mathbf{u}) \geq E_\delta, \quad \forall \mathbf{u} \in W,$$

- There exist $\varepsilon_0 > 0$ e $R_\delta > 0$, such that, $a + b \in (\lambda_k - \varepsilon_0, \lambda_k)$,

$$J^+(\mathbf{u}) < E_\delta - 1, \quad \forall \mathbf{u} \in R_\delta S_{VZ},$$

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- For given a, b with $a + b \in (\lambda_k - \varepsilon_0, \lambda_k)$ and $\text{dist}(a - b, \sigma(-\Delta)) > \delta$, there exist $D_{a+b,\delta} \in \mathbb{R}$ and $\rho_{a+b,\delta} > R_\delta$ such that

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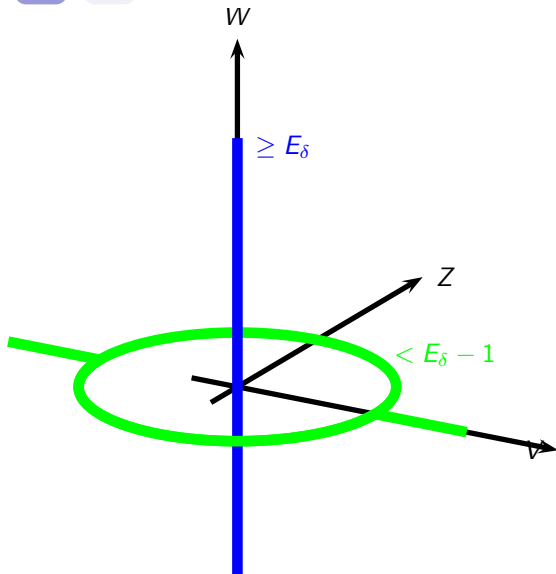
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▶ B1

▶ B2



$V \in W$ have infinite dimension

Para $n > k + m$:
 J_n^+ satisfies (PS).

Saddle Point geometry:

$V_n \in Z \oplus W_n$
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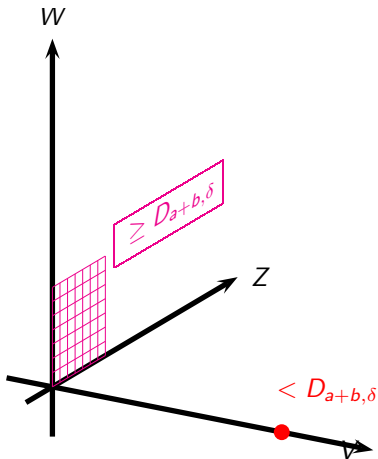
$\exists \mathbf{u}_n, \mathbf{v}_n$, critical points of J_n^+ , at the levels
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Lines of the proof

▶ B1

▶ B2



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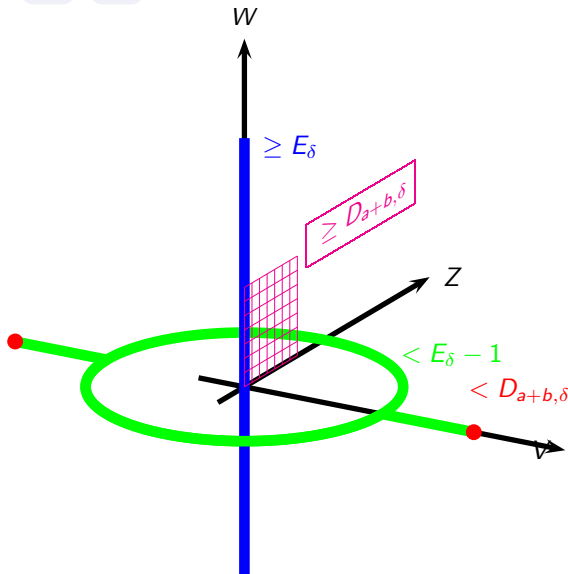
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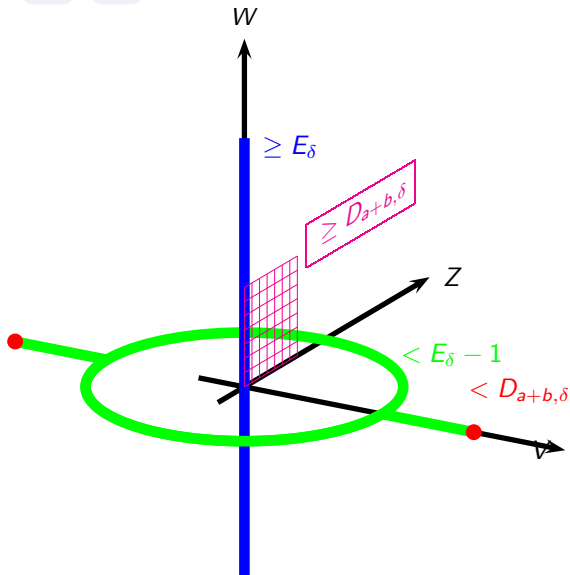
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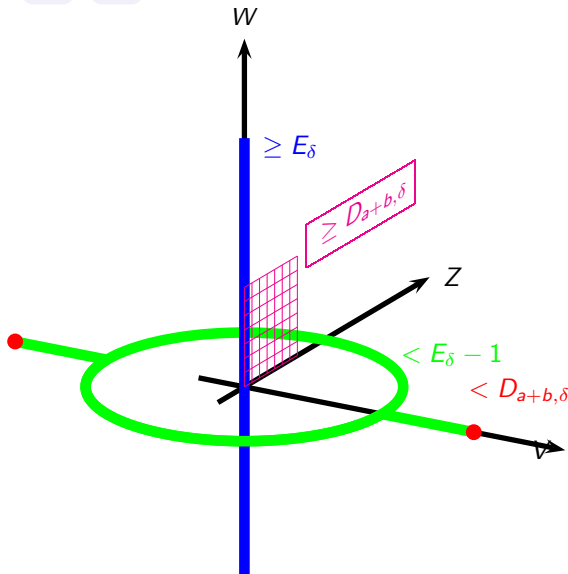
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We prove that $\exists c \in [D_{a+b,\delta}, E_\delta - 1], d \in [E_\delta, T_\delta]$, such that $c_n \rightarrow c, d_n \rightarrow d$.

Moreover there exist critical points $\mathbf{u}, \mathbf{v} \in E$, of the functional J^+ , such that $\mathbf{u}_n \rightarrow \mathbf{u}, \mathbf{v}_n \rightarrow \mathbf{v}, J^+(\mathbf{u}) = c$ and $J^+(\mathbf{v}) = d$.

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Near resonance with the principal eigenvalue

Scalar case: In Ramos-Sanchez (1997) [RS97], three distinct solutions for the scalar problem (1.2 \pm), for $\lambda \in (\lambda_1 - \epsilon, \lambda_1)$ or $\lambda \in (\lambda_1, \lambda_1 + \epsilon)$. (using minimization and Mountain Pass)

Question: Can we find a third solution for the system (1.1 \pm), when $a + b$ or $a - b$ is near λ_1 ?

In Ou-Tang (2009) three solutions are obtained for a gradient System

We need some more regularity: we assume

- Ω a C^2 bounded domain in \mathbb{R}^N ,
- $h_1, h_2 \in L^r(\Omega)$, where $r > N$,
- f_1, f_2 continuous functions in $\overline{\Omega} \times \mathbb{R}$, such that there exist $S > 0$, $q \in (1, 2)$, satisfying

$$|f_i(x, t)| \leq S(1 + |t|^{q-1}), \text{ for } i = 1, 2. \quad (3.1)$$

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We will say

- $\mathbf{u} = (u, v)$ is positive (or negative), when $u > 0$ and $v > 0$ (or $u < 0$ and $v < 0$),

Theorem

Assume the given hypotheses and let $\lambda_h \in \sigma(-\Delta)$ and $Z = \text{span}\{(\phi_1, \phi_1)\}$. Then

- given $\delta > 0$, there exists $\varepsilon_0 > 0$ such that, if $a - b \in (\lambda_{h-1} + \delta, \lambda_h - \delta)$ and $a + b \in (\lambda_1 - \varepsilon_0, \lambda_1)$, then problem (1.1+) has three distinct solutions, of which, one is positive and one is negative.
- given $\delta > 0$, there exists $\varepsilon_1 > 0$ such that, if $a - b \in (\lambda_{h-1} + \delta, \lambda_h - \delta)$ and $a + b \in (\lambda_1, \lambda_1 + \varepsilon_1)$, then problem (1.1-) has three distinct solutions, of which, one is positive and one is negative.



Idea of the proof

First we truncate the nonlinearities: for $i = 1, 2$, we take continuous functions such that

$$\tilde{f}_i(x, s) = \begin{cases} f_i(x, s), & \text{se } s \geq -1, \\ 0, & \text{se } s \leq -2. \end{cases} \quad (4.1)$$

As a consequence hypothesis **(F)** is satisfied, but only at $+\infty$.



Proposition

If $a - b \in (\lambda_{h-1} + \delta, \lambda_h - \delta)$ and $a + b < \lambda_1$, then

- there exists $E_\delta \in \mathbb{R}$, such that $J_{a,b}^+(\mathbf{u}) \geq E_\delta, \forall \mathbf{u} \in W$
- there exist sequences $\varepsilon_j \rightarrow 0^+$ and $R_j \rightarrow +\infty$, (depending on δ), such that if $a + b \in (\lambda_1 - \varepsilon_j, \lambda_1)$, then

$$J_{a,b}^+(\mathbf{u}) < E_\delta - 1, \quad \forall \mathbf{u} \in R_j S_{VZ},$$

$$\tilde{J}_{a,b}^+(\mathbf{u}) < -R_j, \quad \forall \mathbf{u} \in V \text{ with } \|\mathbf{u}\|_E > R_j, \quad \text{▶ A4}$$

$$\tilde{J}_{a,b}^+(\mathbf{u}) < -R_j, \quad \forall \mathbf{u} = \mathbf{v} + k\psi_1, \quad \mathbf{v} \in V, k \geq 0 \text{ and } \|\mathbf{u}\|_E = R_j.$$

- for every j , fixing $a + b \in (\lambda_1 - \varepsilon_j, \lambda_1)$ and $\text{dist}(a - b, \sigma(-\Delta)) > \delta$, there exist $D_{a+b,\delta} \in \mathbb{R}$ and $\rho_{a+b,\delta} > R_j$, such that

$$\tilde{J}_{a,b}^+(\mathbf{u}) \geq D_{a+b,\delta}, \quad \forall \mathbf{u} \in Z \oplus W,$$

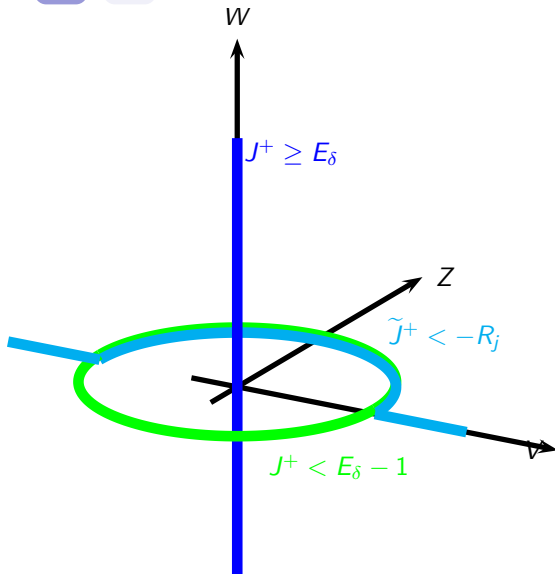
$$\tilde{J}_{a,b}^+(\mathbf{u}) < D_{a+b,\delta}, \quad \forall \mathbf{u} \in \rho S_V, \quad \rho \geq \rho_{a+b,\delta}. \quad \text{▶ A5}$$



Idea of the proof

▶ B4

▶ B5



\exists critical points
 $\tilde{\mathbf{u}}_n^j$ of $\tilde{J}_{a_j, b_j}^+|_{E_n}$ and
 \mathbf{v}_n^j of $J_{a_j, b_j}^+|_{E_n}$,
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$n \rightarrow +\infty :$

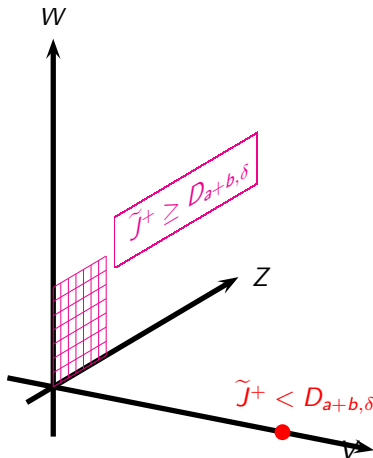
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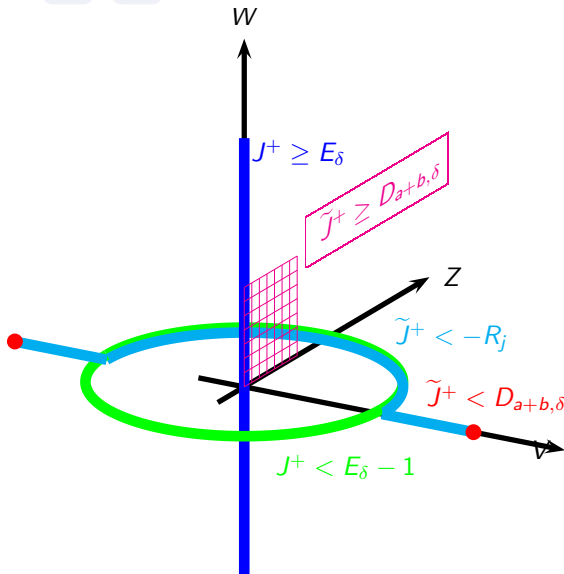
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A sequence of solutions

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\mathbf{v}^j is a solution of

$$\begin{cases} -\Delta u = a_j u + b_j v + (f_1(x, v) + h_1(x)); & \text{em } \Omega, \\ -\Delta v = b_j u + a_j v + (f_2(x, u) + h_2(x)); & \text{em } \Omega, \\ u(x) = v(x) = 0; & \text{em } \partial\Omega. \end{cases} \quad (4.2)$$

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We denote, for every $j \in \mathbb{N}$,

$$\tilde{\mathbf{u}}^j = \beta_j \psi_1 + \omega_j, \quad (4.4)$$

where $\beta_j \in \mathbb{R}$ and $\omega_j \in V \oplus W$.

- Given $\eta > 0$, there exists $\tilde{C}_\eta > 0$ (not depending on j), such that

$$\|\omega_j\|_{C^1 \times C^1} \leq \eta |\beta_j| + \tilde{C}_\eta. \quad (4.5)$$

- $|\beta_j| \rightarrow +\infty$ (since $\tilde{J}_{a_j, b_j}^+(\tilde{\mathbf{u}}^j) = \tilde{c}^j \rightarrow -\infty$)



$$\frac{\tilde{\mathbf{u}}^j}{\beta_j} = \psi_1 + \frac{\omega_j}{\beta_j} \rightarrow \psi_1, \text{ in } C^1(\bar{\Omega}) \times C^1(\bar{\Omega})$$

Then, $\exists j_0$, such that $\forall j \geq j_0$, $\tilde{\mathbf{u}}^j$ is positive, if $\beta_j > 0$, or negative, if $\beta_j < 0$.

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- Then, for every $j > j_0$, we have that $\tilde{\mathbf{u}}^j$ is positive and then it is a solution of (1.1+).
- At this point we have two solutions: $\tilde{\mathbf{u}}^j$ e \mathbf{v}^j : they are distinct since they lie at different levels.

For the third solutions, we consider the system

$$\begin{cases} -\Delta u = au + bv + (-f_1(x, -v) + (-h_1(x))); & \text{in } \Omega, \\ -\Delta v = bu + av + (-f_2(x, -u) + (-h_2(x))); & \text{in } \Omega, \\ u(x) = v(x) = 0; & \text{on } \partial\Omega. \end{cases} \quad (4.6)$$

- if (u, v) is a solution of (4.6), then $(-u, -v)$ is a solution of (1.1+)
- if $\hat{J}_{a,b}$ is the functional associated to (4.6), then $\hat{J}_{a,b}(\mathbf{u}) = J_{a,b}^+(-\mathbf{u})$, $\forall \mathbf{u} \in E$
- $g_i(x, t) = -f_i(x, -t)$ satisfy the same hypotheses as f_i .



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For the third solutions, we consider the system

$$\begin{cases} -\Delta u = au + bv + (-f_1(x, -v) + (-h_1(x))); & \text{in } \Omega, \\ -\Delta v = bu + av + (-f_2(x, -u) + (-h_2(x))); & \text{in } \Omega, \\ u(x) = v(x) = 0; & \text{on } \partial\Omega. \end{cases} \quad (4.6)$$

- if (u, v) is a solution of (4.6), then $(-u, -v)$ is a solution of (1.1+)
- if $\hat{J}_{a,b}$ is the functional associated to (4.6), then $\hat{J}_{a,b}(\mathbf{u}) = J_{a,b}^+(-\mathbf{u})$, $\forall \mathbf{u} \in E$
- $g_i(x, t) = -f_i(x, -t)$ satisfy the same hypotheses as f_i .



Proceeding as before, we get

- there exist $\widehat{\mathbf{u}}^j$ positive solutions of (4.6) for j large, moreover $\widehat{J}_{a_j, b_j}(\widehat{\mathbf{u}}^j) \rightarrow -\infty$.
- then $-\widehat{\mathbf{u}}^j$ are negative solutions of (1.1+) $_j$, and $J_{a_j, b_j}^+(-\widehat{\mathbf{u}}^j) \rightarrow -\infty$.

Conclusion:

$-\widehat{\mathbf{u}}^j \neq \widetilde{\mathbf{u}}^j$: one positive, one negative.

$-\widehat{\mathbf{u}}^j \neq \mathbf{v}^j$: $J_{a_j, b_j}^+(-\widehat{\mathbf{u}}^j) \rightarrow -\infty$ e $J_{a_j, b_j}^+(\mathbf{v}^j) > E_\delta$.

Then (1.1+) has three distinct solutions (of which, one positive and one negative), near enough to the eigenvalue.



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